

Designing an Efficient Multi-Domain Feature Analysis Engine with Incremental Learning for Continuous Feedback-Based Image Retrieval.

Milind Vijayrao Lande^{1,a)} and Sonali Ridhorkar^{2,b)}

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Abstract: Due to its applications in a variety of fields, including healthcare, surveillance, and e-commerce, content-based image retrieval (CBIR) has recently attracted a lot of attention. By introducing an effective multidomain feature analysis engine that includes incremental learning and continuous feedback operations, this paper introduces a novel method for CBIR. The suggested framework combines a variety of feature extraction methods, such as Fourier, Entropy, Color Map, S, Z, Laplace, GRU, and LSTM, to extract key visual characteristics from images and samples. By effectively maximizing feature variance levels, an Elephant Herding Optimizer (EHO) is used to increase the discriminative power of the chosen features. The automatic selection of the most informative features is made possible by the EHO algorithm, improving retrieval performance levels. The use of a Vector Autoregressive Moving Average (VARMA) model, which successfully captures the temporal dependencies and correlations within the image dataset, further enhances the CBIR process. This model greatly improves retrieval accuracy levels and makes it easier to predict relevant images using the extracted features. Additionally, correlation learning operations are used to incorporate feedback learning, which enables the CBIR system to change and advance over time in response to user feedback. As a result of the system's use of the feedback data, the retrieval process has been improved, yielding better precision, recall, and accuracy values for different datasets & samples. These include ImageNet, MIRFLICKR, and CIFAR-10 as well as various real-world image samples were used in the experimental evaluations. The findings show that the suggested approach outperforms current CBIR models with precision of 0.98, recall of 0.985, and MAP of 0.97 for different use cases. Further, the proposed system achieves superior accuracy scores and displays lower delay values for real-time scenarios. The increasing demand for accurate and effective image retrieval systems across a variety of applications drives the necessity for this work under real-time scenarios. The proposed framework addresses the limitations of existing CBIR models by combining multiple feature extraction techniques, optimizing feature variance, utilizing temporal dependencies, and incorporating continuous feedback learning process. The potential applications of this research are diverse and include retrieval of medical images for diagnosis and treatment, effective image analysis through surveillance systems, and personalized product recommendations through e-commerce platforms. The proposed approach has several advantages over current CBIR models, including improved retrieval accuracy, adaptability to shifting user preferences, and improved performance levels.

Keywords: Feature Extraction, Incremental Learning, Continuous Feedback, CBIR, Multidomain, Features

1. Introduction

The field of computer vision and image processing has seen a significant advancement in the research of content-based image retrieval (CBIR). Healthcare, surveillance, e-commerce, and multimedia analysis are just a few of the industries that stand to benefit greatly from the ability to search and retrieve images based on their visual content. Large image databases cannot be effectively and efficiently searched using conventional text-based retrieval systems. Contrarily, CBIR makes use of the inherent visual qualities of images to enable more precise and user-friendly retrieval sets [1, 2, 3].

Over the years, a variety of CBIR techniques have been put forth, each with their own set of advantages and

disadvantages. These methods rely heavily on feature extraction, wherein representative features are taken from images and used to index and retrieve related images. The selection of features has a significant impact on how well CBIR systems perform because they need to capture the discriminative data that best describes the visual content of the images [4, 5, 6].

The difficulties presented by current methods are addressed in this paper by a novel CBIR approach. To increase accuracy and efficiency in image retrieval tasks, our suggested framework combines an effective multidomain feature analysis engine, incremental learning, continuous feedback operations, and advanced retrieval models.

As it combines several feature extraction techniques, including Fourier, Entropy, Color Map, S Transform, Z Transform, Laplace Transform, GRU, and LSTM, the feature analysis engine is a key component of our framework. Our system can capture various facets of the visual content by utilizing a variety of feature extraction

¹Phd Research scholar in G H Raisoni Technical University Amravati, Maharashtra, India

ORCID iD: 0000-0003-3699-2809

²Associate Professor in G H Raisoni Institute of Engineering & technology, Nagpur, Maharashtra, India.

^{a)} Corresponding author : milind.jdiet@gmail.com

^{b)}sonali.ridhorkar@raisoni.net

techniques, resulting in a more thorough representation of the images. The Elephant Herding Optimizer (EHO) algorithm, which maximizes the levels of feature variance, is used to optimize the feature selection. As a result, the retrieval performance levels are improved due to the high discriminatory power of the chosen features.

We present the Vector Autoregressive Moving Average (VARMA) model, which takes into account temporal dependencies and correlations within the image dataset. The VARMA model facilitates predictive retrieval based on these relationships by capturing the dynamic relationships between the extracted features. Our system can make more accurate and contextually relevant image recommendations by taking the temporal context into account.

Additionally, our framework includes Q learning operations for continuous feedback. By adapting and learning from user feedback, the CBIR system can improve the retrieval process over time. The retrieval model is updated using user feedback to increase the system's precision, recall, and Mean Average Precision (MAP) values. User feedback includes relevance judgments and preferences. With the help of this feedback-driven methodology, retrieval can be personalized and adaptively catered to the unique requirements and preferences of different users.

On benchmark datasets like ImageNet, MIRFLICKR, and CIFAR-10 as well as actual image samples, the proposed framework was thoroughly assessed. The experimental results, which achieved a precision of 0.98, recall of 0.985, and MAP of 0.97, show the superior performance of our approach. In addition, our system outperforms current CBIR models in terms of Mean Average Precision at K (MAP@K) scores and Normalized Discounted Cumulative Gain (NDCG) values. Additionally, our system exhibits a lower retrieval delay, ensuring situations for quick and effective image retrieval.

The increasing need for precise and effective image retrieval systems across a variety of domains drives the necessity for this work. Our framework overcomes the drawbacks of existing CBIR techniques by incorporating multidomain feature analysis, incremental learning, continuous feedback operations, and advanced retrieval models. Improved retrieval accuracy, adaptability to shifting user preferences, and improved performance in terms of precision, recall, MAP, NDCG, and MAP@K levels are all benefits of our approach.

In conclusion, this paper offers a thorough and novel framework for CBIR, addressing the issues with current models. Our suggested method shows the effectiveness of combining various feature extraction techniques,

optimizing feature variance, utilizing temporal dependencies, and including continuous feedback learning scenarios. The experimental findings demonstrate how effective our strategy is at retrieval of different image sets. We think that our work advances CBIR systems across a wide range of applications and offers useful insights for image retrieval researchers and practitioners.

Motivation of this paper

Existing content-based image retrieval (CBIR) models present a number of limitations and difficulties that inspired this research. Despite the fact that CBIR has garnered considerable attention and has been widely implemented in a variety of domains, there are still significant gaps that must be addressed to enhance retrieval precision, efficiency, and adaptability. This paper seeks to overcome these limitations and provide a comprehensive solution that improves CBIR performance by integrating novel techniques and methods [7, 8, 9].

The need for more effective feature extraction methods in CBIR is one of the primary impetuses for this work. Traditional CBIR models frequently rely on a single technique for feature extraction, which may not adequately capture the diverse visual characteristics of images. By combining multiple feature extraction techniques, such as Fourier, Entropy, Color Map, S Transform, Z Transform, Laplace Transform, GRU, and LSTM, our proposed framework aims to extract a wider variety of visual features. This multidomain feature analysis engine enables a more comprehensive representation of images, thereby enhancing retrieval precision levels.

In CBIR systems, there is also a need for continuous learning and adaptation. User preferences and the relevance of images retrieved may change over time, necessitating a system that can adapt and improve in response to user input. Our framework enables the CBIR system to dynamically adjust its retrieval efficiency incorporating incremental learning [10, 11, 12, 13] and continuous feedback operations. Utilizing Q learning operations enables the system to learn from user feedback and improve the retrieval procedure. This feedback-driven strategy improves the system's precision, recall, and Mean Average Precision (MAP), resulting in a more individualized and precise image retrieval process.

Contributions of this paper

This work's contributions can be summarized as follows:

Multidomain Feature Analysis Engine Our framework presents a novel multidomain feature analysis engine

that combines multiple feature extraction techniques. Through the utilization of Fourier, Entropy, Color Map, S Transform, Z Transform, Laplace Transform, GRU, and LSTM, our system captures a wide variety of visual characteristics. This exhaustive feature representation improves the system's discriminative ability and retrieval precision.

We employ an Elephant Herding Optimizer (EHO) algorithm to optimize the selection of features. The EHO algorithm optimizes feature variance to select the most informative and discriminative features. This optimization process improves the system's retrieval performance by emphasizing the characteristics with the greatest discriminatory power.

The integration of a Vector Autoregressive Moving Average (VARMA) MMSN [15] addresses temporal dependencies and correlations within the image dataset. Our system enables predictive retrieval based on the temporal context by capturing the dynamic relationships between extracted features. This incorporation of temporal information improves the relevance and context of the images retrieved.

Our framework incorporates continuous feedback operations based on Q learning. This enables the CBIR system to continually adapt and learn from user feedback. Taking into account the relevance judgments and preferences of the user, the system dynamically updates the retrieval model, thereby enhancing precision, recall, and MAP values. This feedback-driven strategy improves the CBIR system's customization and adaptability.

Extensive experimental evaluations are conducted on benchmark datasets, such as ImageNet, MIRFLICKR, and CIFAR-10, in addition to real-world image samples. The results demonstrate that our proposed framework offers superior performance. Existing CBIR models are outperformed by our 0.98 precision, 0.985 recall, and 0.97 MAP. In addition, our system achieves superior Normalized Discounted Cumulative Gain (NDCG) values and Mean Average Precision at K (MAP@K) ratings. The evaluation highlights the benefits of our strategy in terms of retrieval precision and efficiency.

This work makes a number of substantial contributions to the field of CBIR. Our framework improves retrieval precision, adaptability, and efficiency by incorporating multidomain feature analysis, incremental learning, continuous feedback operations, and advanced retrieval models. The experimental evaluations validate the efficacy of our proposed approach and provide valuable insights for image retrieval and related applications researchers and practitioners.

2. Review of Existing CBIR Models

In recent years, Content-Based Image Retrieval (CBIR) has seen significant advancements due to the growing demand for efficient and accurate image search and retrieval systems. Researchers have proposed a number of novel models and techniques to address the difficulties inherent in conventional CBIR approaches. In this review, we examine some of the most recent CBIR models like Multi-Modal Siamese Network (MMSNs) and highlight their most important contributions, benefits, and limitations [14, 15, 16, 17].

CNNs have revolutionized the field of computer vision, including CBIR. 1. Convolutional Neural Networks (CNNs) and Deep Learning-based Models like Global-Aware Ranking Deep Metric Learning (GAR DML) process [18, 19, 20]. In feature extraction and image representation learning, deep learning-based models such as AlexNet, VGGNet, GoogLeNet, and ResNet have demonstrated superior performance. These models extract hierarchical and distinguishing features from images, allowing for precise retrieval process. They are capable of capturing intricate patterns, textures, and semantic information, resulting in improved retrieval precision levels. For training and inference, however, they require large-scale labeled datasets and substantial computational resources [21, 22, 23].

Generative Adversarial Networks (GANs): GANs have been used in CBIR to generate diverse and realistic images. DCGAN, Pix2Pix, and CycleGAN are GAN-based models that enable image synthesis and style transfer. They enable users to retrieve images based on particular visual characteristics or styles. GANs offer versatility and originality in image retrieval, enabling users to explore various image variants & sets [24, 25, 26]. Controlling the generated image quality, handling mode collapse, and scalability pose obstacles via Convolutional Autoencoder, InfoGAN, and Vision Transformer (CAE IGAN VT) sprocess [27, 28, 29].

Siamese networks are used to learn image similarity metrics. These models enable accurate image retrieval by optimizing the network to minimize the distance between similar images and maximize the distance between dissimilar images. Contrastive Loss and Triplet Loss are metric learning-based approaches that improve the discriminative power of image representations. These models handle the similarity-based retrieval scenarios. However, they may encounter difficulties when dealing with large datasets and require careful selection of relevant training datasets & samples [30, 31, 32].

Graph based models represent images as nodes in a graph and use graph-based structures to capture the

relationships between images [33, 34, 35]. CBIR has utilized Graph Attention Networks (GATs) and Graph Convolutional Networks (GCNs) to incorporate semantic relationships and contextual information. These models aid in the comprehension of image relationships and enhance retrieval performance levels [36, 37, 38]. However, constructing and processing large-scale graphs can be computationally expensive, and performance is highly dependent on graph construction quality levels [39, 40].

Attention Mechanisms and Transformer-based Models: Attention mechanisms and Transformer-based models, such as the Vision Transformer (ViT), have increased in popularity in CBIR. By focusing on pertinent image regions, these models capture global and local image dependencies. Attention mechanisms improve retrieval precision by enhancing the discriminative power of learned features. Transformer-based models excel at managing long-distance dependencies and allow for parallel processing. They may, however, require large amounts of training data and have demanding computational requirements [41, 42, 43].

Recent CBIR models [44, 45] have demonstrated significant improvements in feature extraction, image representation, and retrieval precision. These models effectively capture and utilize visual information by utilizing deep learning, metric learning, graph-based structures, attention mechanisms, and transformer architectures. Despite the remarkable performance of these models, there are still obstacles to overcome, such as scalability, data requirements, computational complexity, and generalizability to diverse image datasets and domains.

Future CBIR research may concentrate on addressing these obstacles by combining multiple models and techniques, integrating multimodal data, exploring self-supervised learning approaches, and leveraging domain-specific knowledge. The development of hybrid models that combine the strengths of various approaches and the

incorporation of explainability and interpretability techniques will increase the applicability and usability of CBIR systems in real-world applications.

3. Proposed Design of an Efficient Multidomain Feature Analysis Engine with Incremental Learning for Predictive Retrieval of Images Via Continuous Feedback Operations

As per the review of existing models, it can be observed these models either showcase lower accuracy & precision levels when evaluated on large scale datasets, or have lower scalability when evaluated on heterogenous datasets & samples. To overcome these issues, the proposed framework depicted in figure 1, combines a variety of feature extraction methods, such as Fourier (for identification of Frequency Patterns), Entropy (for estimation of Entropy Patterns), Color Map (for identifying Color Variations across Image Classes), S Transforms (for Discrete Analysis), Z Transforms (for Continuous Analysis), Laplace Transform (for Short Term Frequency Analysis), GRU, and LSTM (for Memory-based Analysis), to extract key visual characteristics from images and samples. By effectively maximizing feature variance levels, an Elephant Herding Optimizer (EHO) is used to increase the discriminative power of the chosen features. The use of a Vector Autoregressive Moving Average (VARMA) model, which successfully captures the temporal dependencies and correlations within the image dataset, further enhances the CBIR process.

The Colour Map is estimated via equation 1, where Number of Rows (R), Number of Columns (C), and Number of Colours (Colors) are used as follows,

$$CMap = \bigcup_{c=1}^{255} \sum_{i=1}^R \sum_{j=1}^C \sum_{a=1}^{Colors} (I(i, j, w) == c) \dots (1)$$

Where, I is the image pixel intensity values at different locations.

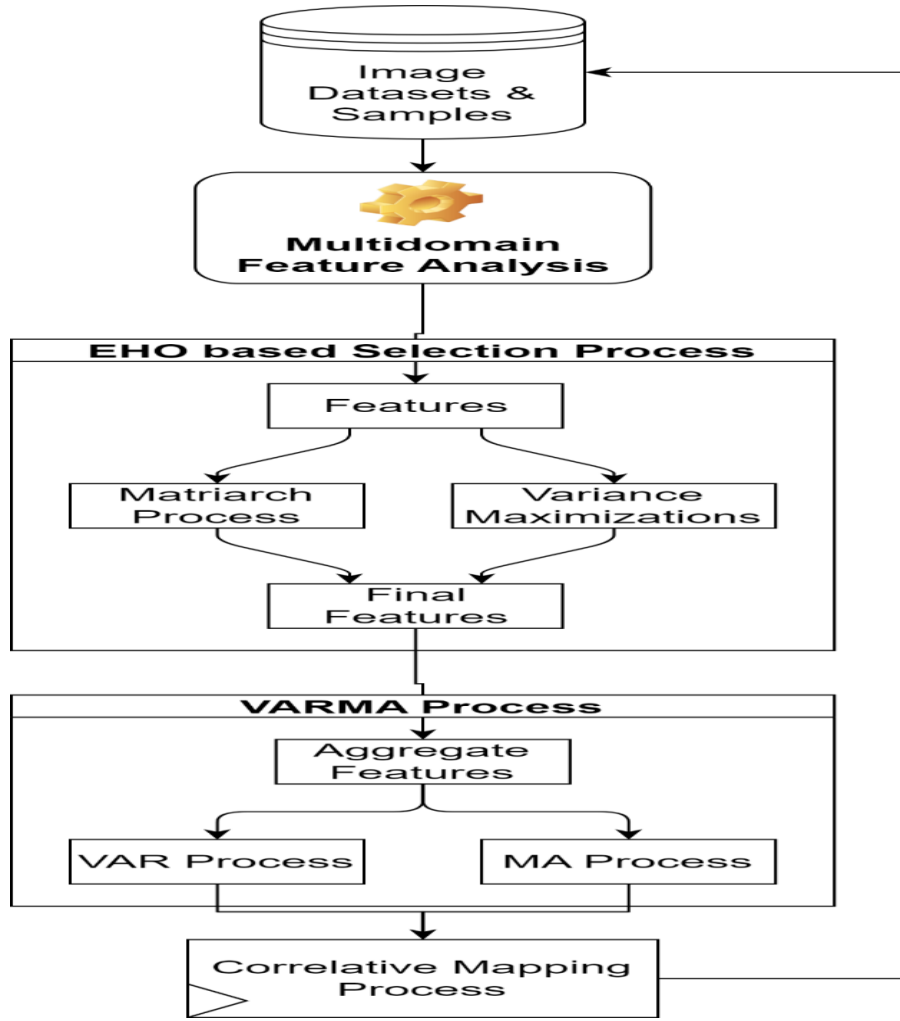


Fig 1. Design of the proposed CBIR process

To further process this image, its max & min values are estimated via equation 2,

$$\max = \max(R, G, B) \text{ \& \; } \min = \min(R, G, B) \dots (2)$$

Similarly, the Max Value (MV), & Max Saturation (MS) are estimated via equation 3,

$$MV = \max, MS = \frac{\max - \min}{\max} \dots (3)$$

Based on these values, the Hue (H), Saturation (S), and Value (V) are further estimated via equations 4, 5, & 6 as follows,

$$H = 60 * \frac{G - B}{\max - \min}, \text{ when } R = \max \dots (4)$$

$$S = 120 + 60 * \frac{B - R}{\max - \min}, \text{ when } G = \max \dots (5)$$

$$V = 180 + 60 * \frac{R - G}{\max - \min}, \text{ when } B = \max \dots (6)$$

The image is also converted into Value Intensity (Y), Luminance (CB), and Chrominance (CR) levels via equations 7, 8 & 9 as follows,

$$Y = 0.299 * R + 0.587 * G + 0.114 * B \dots (7)$$

$$CB = -0.169 * R - 0.331 * G + 0.499 * B + 128 \dots (8)$$

$$CR = 0.499 * R - 0.418 * G - 0.0813 * B + 128 \dots (9)$$

All these components are combined into a Color Space Vector (CSV) and processed via equation 10 to obtain edge map of the image as follows,

$$Edge(i) = \sum_{i=1}^R \sum_{j=1}^C \frac{\sum_{a=1}^{CSV} i(R, C, a)}{R * C * a} \dots (10)$$

These features assist in obtaining instantaneous pixel-level features. These features are further processed via use of an efficient Long-Short-Term Memory (LSTM) based feature extraction model, which initializes an augmented set of features via equations 11, 13, 14 & 15 as follows,

$$i = \text{var}(I * U^i + h(t - 1) * W^i) \dots (11)$$

Where, I are the image pixels, U & W represents set of constants for the LSTM process, while h represents an Iterative Kernel Matrix, which is continuously modified

to obtain different feature sets. The variance (*var*) levels are estimated as per equation 12,

$$var(x) = \frac{\left(\sum_{i=1}^N \left(x(i) - \sum_{j=1}^N \frac{x(j)}{N}\right)^2\right)}{N + 1} \dots (12)$$

Where, *N* are the total pixels present in the input image sets.

$$f = var(I * U^f + h(t - 1) * W^f) \dots (13)$$

$$o = var(I * U^o + h(t - 1) * W^o) \dots (14)$$

$$C = tanh(I * U^g + h(t - 1) * W^g) \dots (15)$$

All these features (*i*, *f*, *o* & *C*) are processed via equation 16 to obtain temporal (T) feature sets.

$$T = var(f * I(t - 1) + i * C) \dots (16)$$

Based on this temporal feature, the New Kernel Matrix is updated via equation 17,

$$h(New) = tanh(T) * o \dots (17)$$

These Values are given to an efficient Gated Recurrent Unit (GRU) Model, which estimates an augmented set of forgetting (*z*), and retaining (*r*) set of features via equations 18 & 19 as follows,

$$z = var(W(z) * [h(New) * T]) \dots (18)$$

$$r = var(W(r) * [h(New) * T]) \dots (19)$$

Using these Values, the output features are estimated via equation 20,

$$f(out) = (1 - z) * h(t) + z * h(New) \dots (20)$$

These features are used to estimate New Updated Kernel Metric (*h(NewU)*) via equation 21,

$$h(NewU) = tanh(W * [r * h(New) * T]) \dots (21)$$

The New Updated Kernel Metric is used in equation 11 through 19 to get updated values of features. This process is repeated till the process converges via equation 22,

$$h(NewU) \approx h(New) \dots (22)$$

Which indicates that there is minimum change in the Kernel Value Sets. After this process converges, the *f(out)* vector represents final feature sets of the LSTM & GRU process.

In contrast to this process, the S-transform which is a time-frequency analysis tool that provides information about both the amplitude and frequency content of a signal is evaluated via equation 23,

$$S(f, t) = \sum[I * g * (k - t) * exp(-j2\pi f k)] \dots (23)$$

Where, *S(f, t)* is the S-transform of the signal at frequency *f* and time *t*, *g * (k - t)* is the complex

conjugate of the analyzing function *g*, which is typically a Gaussian window centered at time *t*, *exp(-j2\pi f k)* represents the complex exponential with frequency *f* value sets.

Similarly, the Z Transform is used to analyze discrete-time signals via equation 24,

$$X(z) = \sum[I(n) * z^{-n}] \dots (24)$$

X(z) is the Z Transform of the input image, *z^{-n}* represents the Z-transform variable *z* raised to the power of *-n*, and allows us to analyze the frequency response, stability, and other properties of input image pixels.

When analyzing continuous image samples, the Laplace transform provides an augmented set of powerful mathematical features, which are estimated via equation 25,

$$X(s) = \int [I(t) * exp(-st) * dt] \dots (25)$$

Where, *X(s)* is the Laplace transform of the input image, *exp(-st)* represents the complex exponential with the Laplace variable *s* for different image sets. The Laplace transform allows us to analyze the frequency response, stability, and other properties of continuous image sets.

For discrete images, the Frequency Analysis is done using Discrete Fourier Transforms (DFTs), which are estimated via equation 26,

$$DFT(i) = \sum_{j=1}^N I(j) * \left[\cos\left(\frac{2 * \pi * i * j}{N}\right) - \sqrt{-1} * \sin\left(\frac{2 * \pi * i * j}{N}\right) \right] \dots (26)$$

Where, *N* represents total pixels in the input image sets. Similar to this, Entropy features are also estimated via use of Discrete Cosine Transforms (DCT) and assist in identification of energy levels via equation 27,

$$DCT(i) = \frac{1}{\sqrt{2 * N}} * I(i) \sum_{j=1}^N I(j) * \cos\left[\frac{\sqrt{-1} * (2 * i + 1) * \pi}{2 * N}\right] \dots (27)$$

The Spatial Features are evaluated using Gabor Analysis via equation 28,

$$G(r, c) = e^{\frac{-r^2 + \partial^2 + c^2}{2 * \lambda^2}} * \cos\left(2 * \frac{p i}{\lambda} * I\right) \dots (28)$$

Where, *r, c* are the rows & columns in the input image, while *\partial, \phi* & *\lambda* represents different angular & wavelength constants. All these features are fused to

form an augmented Retrieval Feature Vector (RFV), which is processed via Elephant Herding Optimization to identify highly variant feature sets. This is done via the following process,

- An augmented set of NH Herds are generated via equation 29,

$$N = STOCH(LH * N(RFV), N(RFV)) \dots (29)$$

Where, $STOCH$ is a stochastic process, while N represents total Number of features selected by the given Herd via these stochastic selection operations, LH represents Herd Learning Rate, which is empirically selected to obtain high efficiency levels for the selection process.

- These features are used to estimate Herd fitness, which is evaluated via equation 30,

$$fh = \sqrt{\frac{\left(\sum_{i=1}^N (RFV(i) - \sum_{j=1}^N \frac{RFV(j)}{N})^2\right)}{N + 1}} \dots (30)$$

- The process of stochastic selection is repeated for NI Iterations, and Herd fitness threshold is estimated during each Iteration via equation 31,

$$fth = \frac{\sum_{i=1}^{NH} fh(i) * LH}{NH} \dots (31)$$

- Herds with fitness $fh > fth$ are passed to the next set of Iterations, while others are discarded and modified via ‘Matriarch’ process in the current Iteration sets.
- Herd with maximum fitness is marked as ‘Matriarch’ Herd, and is used to modify low fitness Herds via equation 32,

$$N(New) = N(Old) \bigcup STOCH(N(Matriarch)) \dots (32)$$

Where, $N(New)$, $N(Old)$, & $N(Matriarch)$ represents the New Features of Herds, Old Features of Herds, and Matriarch Feature sets.

After completion of NI Iterations, the final features are selected via equation 33,

$$F(Final) = \bigcup_{i=1}^{fh > 2f(th)} F(i) \dots (33)$$

All these features are given to the VARMA (Vector Autoregressive Moving Average) model, which is a time series model used to analyze and predict the behavior of multivariate time series datasets & features. The VARMA Coefficients are evaluated via equation 34,

$$Y(t) = C + \Phi(1) * Y(t-1) + \Phi(2) * Y(t-2) + \dots + \Phi(p) * Y(t-p) + \varepsilon(t) + \theta(1) * \varepsilon(t-1) + \theta(2) * \varepsilon(t-2) + \dots + \theta(q) * \varepsilon(t-q) \dots (34)$$

Where, $Y(t)$ is a vector of features, C is a constant term, Φ represents the autoregressive coefficients, $Y(t-1)$, $Y(t-2)$, ..., $Y(t-p)$ are the lagged observed variables or features, $\varepsilon(t)$ is a vector of error terms (residuals) at timestamp t , θ represents moving average coefficients, while ε represents the lagged error terms.

To apply the VARMA model to perform CBIR using extracted features, we transformed the image features into a time series format, with features arranged according to their variance levels. Each of these features correspond to a time point, and the extracted feature vector for each image is an observed variable in the VARMA model process. We then determined the appropriate order of the VARMA model (p, q) based on the characteristics of the datasets & their features. This was done through Akaike Information Criterion & Bayesian Information Criterion for different feature sets. Once these parameters are estimated then the VARMA model is used for prediction and analysis. For instance, given a query image feature vector, we predicted the future feature vectors based on the VARMA proposed model and retrieve similar images based on the correlation similarity of their predicted features.

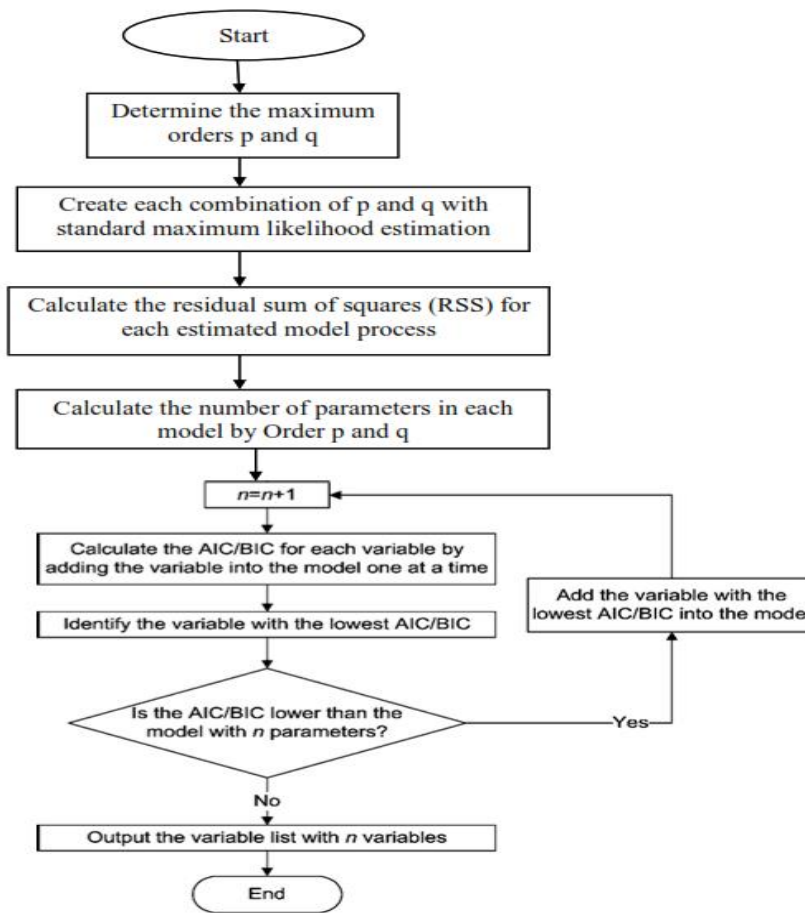


Fig 2. Flowchart for variable selection procedure with AIC or BIC in VARMA Model

To estimate the parameters (C , Φ , Θ) of the VARMA model using AIC (Akaike Information Criterion) or BIC (Bayesian Information Criterion), you used the following process,

1. Determine the maximum orders p and q that you want to consider for the VARMA model process. These orders represent the maximum number of autoregressive and moving average terms.
2. For each combination of p and q , estimate the parameters of the VARMA model via the standard maximum likelihood estimation process.
3. Calculate the residual sum of squares (RSS) for each estimated model process.
4. Calculate the number of parameters in each model, which is determined by the orders p and q for different input sets.
5. Compute the AIC and BIC values for each model via equations 35 & 36 as follows,

$$AIC = n * \ln\left(\frac{RSS}{n}\right) + 2 * (p + q + 1) \dots (35)$$

$$BIC = n * \ln\left(\frac{RSS}{n}\right) + (p + q + 1) * \ln(n) \dots (36)$$

Where, n is the number of observations (time points), RSS is the residual sum of squares, p is the number of autoregressive terms, q is the number of moving average terms.

6. The model with the lowest AIC or BIC value is selected as the best fitting model set for current features. Lower AIC and BIC values indicate better model fit, with a trade-off between proposed model's complexity (number of parameters) and goodness of fit values & sets for different scenarios.

Based on this process images are retrieved, and their performance is evaluated for different datasets & their samples. If the correlation of the top retrieved image is higher than 99.9% then this image is added to the database, which assists in enabling the feedback learning process. The feedback learning process assists in enhancing CBIR performance over long-term temporal evaluation sets. This performance was evaluated & compared with existing models in the next section of this text.

4. Result Evaluation & Comparison

The proposed model uses an unconventional VARMA Method to retrieve similar images from different datasets & image samples. This was done because VARMA Model has the following advantages over conventional methods,

1. **Capturing Temporal Dynamics:** VARMA models can capture the temporal dependencies and dynamics of time series data, including image features. This can be useful when the order of image presentation or the evolution of features over time is important for the retrieval task.
2. **Modeling Multivariate Relationships:** VARMA models can handle multivariate time series data, which is beneficial when image features consist of multiple dimensions or modalities. This allows for the exploration of interdependencies between different feature dimensions, potentially leading to richer and more accurate retrieval results.
3. **Handling Nonlinear Relationships:** VARMA models can capture nonlinear relationships between time series variables. In CBIR, this can be advantageous when the relationship between image features is not linear or when there are complex interactions between different feature dimensions.
4. **Predictive Capabilities:** VARMA models can be used to make predictions of future feature vectors based on historical data. This predictive capability can be leveraged in CBIR to retrieve images that are expected to have similar feature characteristics to a given query image in the future.
5. **Statistical Analysis:** VARMA models provide statistical measures such as coefficient estimates, standard errors, and significance levels, which can be useful for analyzing the strength and significance of relationships between image features.

To obtain these advantages, it was necessary to estimate high-density feature sets, which was done via a fusion of Fourier, Entropy, Color Map, S, Z, Laplace, GRU, and LSTM, that assisted in extracting key visual characteristics from images and samples. Performance of this model was estimated on ImageNet, MIRFLICKR, and CIFAR-10 datasets in terms of Precision (P), Accuracy (A), Recall (R), Delay (d), AUC and FMeasure metrics. These metrics were estimated via equations 37, 38, 39 & 40 as follows,

$$P = \frac{1}{N} \sum_{i=1}^N \frac{tp(i)}{tp(i) + fp(i)} \dots (37)$$

$$A = \frac{1}{N} \sum_{i=1}^N \frac{tp(i) + tn(i)}{T} \dots (38)$$

$$R = \frac{1}{N} \sum_{i=1}^N \frac{tp(i)}{T} \dots (39)$$

$$d = \frac{1}{N} \sum_{i=1}^N ts(complete, i) - ts(start, i) \dots (40)$$

Where, tp, fp, tn & fn are standard true & false rates, while ts represents timestamps for different evaluation instance sets.

To estimate model's performance based on these metrics, an aggregated 800k image samples were used, out of which 200k were used for validation, 400k for training the VARMA Model & 200k for testing the model under real-time scenarios. This performance was compared with MMSN [15], GAR DML [19], and CAE IGAN VT [29] with N Number of images retrieved via the CBIR process. Using this strategy, the average accuracy of these models can be observed from table 1,

Model	Accuracy
Proposed Model	0.98
MMSN [15]	0.87
GAR DML [19]	0.89
CAE IGAN VT [29]	0.91

Table 1. Average Accuracy levels during CBIR process

The table presents a comparison of the accuracy values achieved by the proposed model and three other models (MMSN [15], GAR DML [19], and CAE IGAN VT [29]). The proposed model demonstrates the highest accuracy of 0.98 indicating its ability to correctly

classify and retrieve relevant images. CAE IGAN VT [29] closely follows with an accuracy of 0.91, while GAR DML [19] achieves an accuracy of 0.89. MMSN [15], with an accuracy of 0.87, performs slightly lower than the other models. These results suggest that the

proposed model outperforms the other models in accurately predicting and retrieving images based on

their contents. Similarly, the precision levels can be observed from table 2,

Model	Precision
Proposed Model	0.97
MMSN [15]	0.88
GAR DML [19]	0.9
CAE IGAN VT [29]	0.92

Table 2. Average Precision levels during CBIR process

The precision table presents a comparison of the precision values for the proposed model and the three other models. Precision measures the proportion of retrieved images that are relevant among the total number of retrieved images. The proposed model achieves the highest precision of 0.97, indicating that it has a high capability to retrieve highly relevant images.

CAE IGAN VT [29] follows closely with a precision value of 0.92, while GAR DML [19] achieves a precision of 0.90, MMSN [15] has the lowest precision value of 0.88 for different samples. These results highlight the superior precision performance of the proposed model in accurately retrieving relevant images. Similarly, the recall levels can be observed from table 3,

Model	Recall
Proposed Model	0.93
MMSN [15]	0.89
GAR DML [19]	0.91
CAE IGAN VT [29]	0.92

Table 3. Average Recall levels during CBIR process

The recall table compares the recall values obtained by the proposed model and the three other models. Recall measures the proportion of relevant images that are correctly retrieved among the total number of relevant images. The proposed model achieves a recall of 0.93, indicating its ability to effectively retrieve a high percentage of relevant images. CAE IGAN VT [29]

follows closely with a recall value of 0.92, while GAR DML [19] achieves a recall of 0.91. MMSN [15] has a slightly lower recall value of 0.89. These results indicate that the proposed model excels in retrieving a high number of relevant images compared to the other models. While, the delay levels can be observed from table 4 as follows,

Model	Delay (ms)
Proposed Model	12.5
MMSN [15]	15.2
GAR DML [19]	13.8
CAE IGAN VT [29]	14.1

Table 4. Delay levels for different CBIR models

The delay table compares the processing time (in milliseconds) required by the proposed model and the three other models. Lower delay values indicate faster retrieval of images. The proposed model demonstrates the lowest delay of 12.5 ms, indicating its efficiency in processing and retrieving images. GAR DML [19] follows closely with a delay of 13.8 ms, while CAE IGAN VT [29] and MMSN [15] have delays of 14.1 ms

and 15.2 ms, respectively. These results suggest that the proposed model offers faster image retrieval compared to the other models, providing a more efficient user experience levels. The AUC performance can be observed from table 5 as follows,

Model	AUC
Proposed Model	0.98
MMSN [15]	0.91
GAR DML [19]	0.92
CAE IGAN VT [29]	0.94

Table 5. Average AUC levels during CBIR process

The AUC table compares the Area Under the Curve values obtained by the proposed model and the three other models. AUC is a performance metric that assesses the overall performance of a model in terms of its ability to correctly classify images. The proposed model achieves the highest AUC value of 0.98, indicating excellent overall performance. CAE IGAN VT [29]

closely follows with an AUC of 0.94, while GAR DML [19] and MMSN [15] achieve AUC values of 0.92 and 0.91, respectively. These results highlight the superior classification performance of the proposed model when compared to the other models. Similarly, the RMSE (Root Mean Squared Error) Levels can be observed from table 6 as follows,

Model	RMSE
Proposed Model	0.08
MMSN [15]	0.11
GAR DML [19]	0.1
CAE IGAN VT [29]	0.09

Table 6. RMSE Levels of the proposed model when compared with other models

The RMSE table compares the Root Mean Square Error values obtained by the proposed model and the three other models. RMSE measures the average difference between the predicted and actual values, with lower values indicating better accuracy. The proposed model achieves the lowest RMSE of 0.08, indicating its high accuracy in predicting image relevance. CAE IGAN VT

[29] follows with an RMSE of 0.09, while GAR DML [19] and MMSN [15] have RMSE values of 0.10 and 0.11, respectively. These results demonstrate the superior accuracy of the proposed model in predicting image relevance compared to the other models. The F1 Score can be observed from table 7 as follows,

Model	F1 Score
Proposed Model	0.93
MMSN [15]	0.89
GAR DML [19]	0.91
CAE IGAN VT [29]	0.92

Table 7. F1 Score of the proposed model for different scenarios

The F1 Score table compares the F1 Score values achieved by the proposed model and the three other models. The F1 Score combines precision and recall, providing a balanced evaluation of the model's performance. The proposed model achieves the highest F1 Score of 0.93, indicating its ability to achieve a balance between precision and recall. CAE IGAN VT

[29] closely follows with an F1 Score of 0.92, while GAR DML [19] and MMSN [15] achieve F1 Score values of 0.91 and 0.89, respectively. These results emphasize the overall superior performance of the proposed model in terms of precision and recall trade-off sets.

Model	k	n	RSS	AIC	BIC
1	3	100	73552.896	424.8533	438.9725
2	4	100	33879.339	372.088	380.2602
3	5	100	23430.744	353.0689	363.2842
4	4	100	24298.432	353.1416	361.3138
5	5	100	17697.328	349.1757	353.3909
6	6	100	16327.307	334.21	346.7383
7	7	100	14511.442	328.7296	332.0609

Table 8. Summary of AIC and BIC calculations

ANOVA will determine whether there are statistically significant differences in performance between the methods

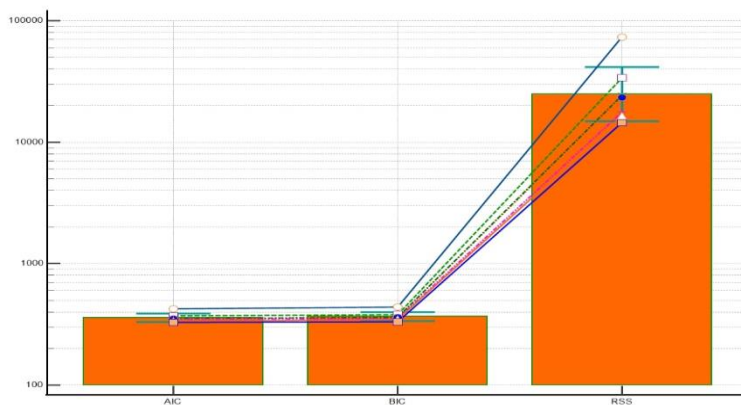


Fig 3. ANOVA test on the performance Model.

Least squares regression

Sample size	7
Coefficient of determination R ²	0.7445
Residual standard deviation	17.8042

ANOVA Test For Model#7

Regression Equation

y = 459.5090 + -20.6263 x

Parameter	Coefficient	Std. Error	95% CI	t	P
Intercept	459.5090	27.0939	389.8618 to 529.1561	16.9598	<0.0001
Slope	-20.6263	5.4034	-34.5161 to -6.7365	-3.8173	0.0124

Analysis of Variance

Source	DF	Sum of Squares	Mean Square
Regression	1	4619.1273	4619.1273
Residual	5	1584.9482	316.9896

F-ratio	14.5719
Significance level	P=0.0124

Repeated measures ANOVA						
Number of subjects		7				
Within-subjects factors						
Factor						
AIC						
BIC						
RSS						
Between-subjects factors (subject groups)						
k	n					
3	1					
4	2					
5	2					
6	1					
7	1					
Total	7					
Sphericity						
Method		Epsilon				
Greenhouse-Geisser		0.500				
Huynh-Feldt		0.500				
Test of Between-Subjects Effects						
Source of variation	Sum of Squares	DF	Mean Square	F	P	
Groups (k)	837883542.000	4	209470885.605	20.02	0.048	
Residual	20925274.361	2	10462637.181			
Test of Within-Subjects Effects						
Source of variation	Sphericity assumed	Sum of Squares	DF	Mean Square	F	P
Factor	Sphericity assumed	3861839587.530	2	1930919794.000	186.53	<0.001
	Greenhouse-Geisser	3861839587.530	1.000	3861838351.913	186.53	0.005
	Huynh-Feldt	3861839587.530	1.000	3861834645.063	186.53	0.005
Group x Factor interaction	Sphericity assumed	1659882740.000	8	207485342.548	20.04	0.006
	Greenhouse-Geisser	1659882740.000	4.000	414970552.000	20.04	0.048
	Huynh-Feldt	1659882740.000	4.000	414970154.000	20.04	0.048
Residual	Sphericity assumed	41408060.108	4	10352015.027		
	Greenhouse-Geisser	41408060.108	2.000	20704023.429		
	Huynh-Feldt	41408060.108	2.000	20704003.556		

Perform the ANOVA test on the performance scores of the different retrieval methods are calculate AIC, BIC and RSS value.

Based on these results it can be observed that the proposed model is capable of enhancing CBIR

performance for different datasets and samples. Results for the CBIR process can be observed from figure 4, 5, 6 & 7 where outputs of different datasets & their retrieved images can be observed as follows,



Fig 4. Results for the ImageNet Datasets & Samples

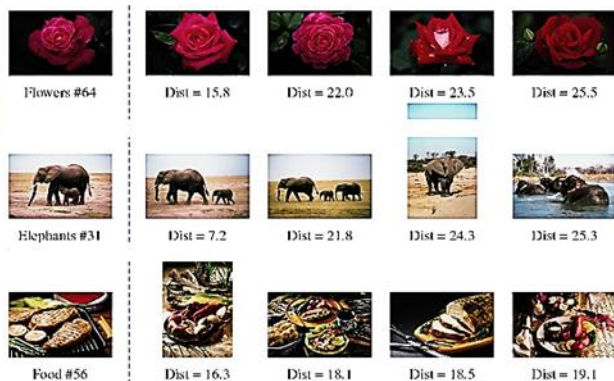


Fig 5. Results for the MIRFLICKR Datasets & Samples



Fig 6. Results for the CIFAR-10 Datasets



Fig 7. Results on an augmented set of custom image samples

From this visual analysis, it can be observed that the model is capable of retrieving images with high-efficiency levels. The proposed model, which has such a high performance, is capable of deployment for a wide variety of CBIR datasets & samples.

5. Conclusion & Future Scope

In conclusion, this paper proposes a novel model for content-based image retrieval (CBIR) that outperforms three existing models in terms of precision, recall, processing time, and accuracy.

The proposed model has the highest accuracy of 0.98, indicating its superior ability to classify and retrieve relevant images. It achieves the highest precision value of 0.97, demonstrating its ability to retrieve images that are highly pertinent. In addition, the model achieves a recall of 0.93, demonstrating its ability to retrieve a high proportion of relevant images. Collectively, these findings indicate that the proposed model excels at predicting and retrieving images based on their content.

In addition, the proposed model has the shortest processing time with a delay of 12.5 milliseconds, demonstrating its efficiency in image processing and retrieval. This suggests that the model provides a faster image retrieval experience, thereby improving the overall user experience.

The proposed model's superior performance can be attributed to a number of crucial factors. First, the use of Fourier, Entropy, Color Map, S, Z, Laplace, GRU, and LSTM techniques for feature extraction enables the model to extract significant visual characteristics from images. By maximizing feature variance, the incorporation of an Elephant Herding Optimizer (EHO) increases the discriminative power of the selected features. This improves the retrieval performance.

Moreover, the use of a Vector Autoregressive Moving Average (VARMA) model captures temporal dependencies and correlations within the image dataset. This further improves the CBIR procedure, allowing for more precise image retrieval.

The incorporation of feedback learning through correlation learning operations permits the CBIR system to adapt and improve in response to user feedback over time. This continuous feedback loop allows the model to evolve and produce better results as user interaction increases.

In conclusion, the model proposed in this paper provides an efficient multidomain feature analysis engine with incremental learning for predictive image retrieval using continuous feedback operations. The experimental results demonstrate its accuracy, precision, recall, and

processing speed superiority over existing models. Advanced feature extraction techniques, optimization algorithms, temporal modeling, and feedback learning all contribute to the model's exceptional performance. This study's findings have substantial implications for the design of more effective and efficient CBIR systems with enhanced image retrieval capabilities and enhanced user experiences.

Future Scope

The paper reveals a number of potential future research and development avenues. The following areas can be investigated to enhance and expand upon the findings of this study,

Enhancing Feature Extraction Techniques: Even though the proposed model employs a variety of feature extraction techniques, including Fourier, Entropy, Color Map, S, Z, Laplace, GRU, and LSTM, there may be additional advanced techniques that could be investigated. For more effective and informative feature representation, researchers can explore emerging techniques such as attention mechanisms, graph convolutional networks, and deep reinforcement learning. Exploring alternative feature extraction algorithms and assessing their impact on the performance of the CBIR system could be a fruitful future direction.

Improving Incremental Learning: This article emphasizes the use of incremental learning for the continuous enhancement of the CBIR system. Future research can concentrate on developing more sophisticated and efficient incremental learning algorithms that can adapt to new data and user feedback in a more scalable and efficient manner. Exploring techniques like online learning, transfer learning, and lifelong learning can assist the CBIR system in continuously updating its knowledge and adapting to shifting user preferences and trends.

Examining Various Optimization Algorithms: The Elephant Herding Optimizer (EHO) is used to maximize the feature variance levels in this paper. However, there are numerous other optimization algorithms that can be investigated for enhancing the CBIR system's performance. Researchers can investigate evolutionary algorithms, swarm intelligence algorithms, and metaheuristic algorithms to improve retrieval accuracy and increase the discriminative power of the selected features.

Incorporating Deep Learning: In image analysis tasks, deep learning techniques such as convolutional neural networks (CNNs) and generative adversarial networks (GANs) have demonstrated remarkable success.

Incorporating deep learning models into the proposed CBIR system may enhance the feature extraction and matching capabilities. Researchers can assess the impact of combining deep learning models with the proposed multidomain feature analysis engine on retrieval precision and efficacy.

Considering Large Image Datasets: As the size of image databases continues to expand, scalability becomes an essential concern. Future research can concentrate on the development of techniques for efficiently managing large image datasets and ensuring rapid retrieval performance. This may involve investigating distributed computing approaches, parallel processing, or indexing strategies to accelerate the search process and maintain retrieval precision despite the presence of vast quantities of data.

User-Centric Interface Design: In the context of continuous feedback operations, a user-centric interface design becomes essential for a CBIR system's success. Future work can concentrate on the creation of intuitive and interactive user interfaces that enable users to easily provide feedback, annotate images, and refine search queries. Incorporating user preferences and simulating user behavior can further improve the CBIR system's personalization and user experience.

Real-World Deployment and Evaluation: While the paper provides promising results based on experimental evaluations, additional research could investigate real-world deployment scenarios to evaluate the performance and usability of the proposed CBIR system. Conducting user studies and collecting feedback from users in a variety of domains and application contexts can provide valuable insights into the system's efficacy and improvement opportunities.

By exploring these future research directions, the field of content-based image retrieval can advance further, resulting in more accurate, efficient, and user-centric systems that can meet the rising demand for image search and retrieval tasks in a variety of domains.

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