

Energy-Efficient Resource Allocation and Relay-Selection for Wireless Sensor Networks

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Submitted: 16/09/2023

Revised: 29/10/2023

Accepted: 16/11/2023

Abstract: We study a cooperative wireless network in the framework of this inquiry. This network is made up of two transceiver nodes that connect with one another through two-way amplify-and-forward (AF) relay nodes that have a limited amount of energy. This network is used to study the problem. The energy that is included inside the signal that has been received is used by the relay nodes in order to magnify the signal before it is retransmitted to the transceiver nodes. As a consequence of this, the transceiver nodes are able to transfer both information and energy at the same time. In order to accomplish simultaneous information extraction and energy harvesting at the relay, we study a time switching-based relaying (TSR) protocol in addition to a power splitting-based relaying (PSR) mechanism. TSR stands for time switching relaying, while PSR stands for power splitting relaying. By using the dual decomposition strategy, we are able to provide a solution to the problem that is close to optimal. The findings of the simulation indicate that the joint resource allocation plan that was recommended fulfils the required requirements for service quality, and that the degree of energy efficiency that may be achieved is greater than that of some projects that are currently being worked on. In addition, the resource allocation approach that has been provided works better in terms of convergence under a variety of topologies. This demonstrates the high scalability of the resource allocation system. The results of an in-depth simulation are presented to illustrate how well our proposed method works in terms of the distribution of transmitting power among the nodes and the overall utility that the network provides. As a consequence of this, there is reason to be positive about the future of practical applications including the joint optimization technique.

Keywords: Energy harvesting, Wireless sensor network, Relay selection, Resource Allocation.

1. Introduction

Batteries are often used as the source of power in wireless devices since this enables the devices to keep their portability. The finite amount of time that the batteries are able to perform their function is a factor that reduces the lifespan of the network. In a more realistic environment,

the fact that there is a desire for the continuous renewal of energy sources presents a number of challenges. If a network is able to collect the energy that is already accessible in its immediate surroundings, there is a possibility that it will be able to get access to a reliable supply of power. In recent times, there has been a lot of interest in the process of extracting energy from “radio-frequency” (RF) signals. Due to the fact that “radio frequency” (RF) broadcasts are capable of carrying both information and energy, communication nodes have the ability to simultaneously gather energy and extract information from RF broadcasts. The authors use a capacity-energy function to illustrate the fundamental trade-offs involved with the simultaneous transport of information and energy. These trade-offs are linked with the simultaneous transmission of both information and energy.

The research consists of both a frequency-selective channel and an additive white Gaussian noise (AWGN) component [1]. The most recent advancements in RF signal-based simultaneous information transmission and energy harvesting usually involve two different methodologies. The first way enables the receiver to do an analysis of the data and distinguish between the different energies included within the same signal. Because RF signal energy harvesting circuits are not yet capable of

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directly reading the data that is being provided by RF signals, it is likely that the implementation of this receiver design will not function very well in reality. It is possible, however, that it will work well in theory. The second tactic takes into consideration the efficient receiver designs that make use of “Time switching” (TS) and “power splitting” (PS). Wireless networks have used cooperative relay technologies in order to enhance network connectivity and make the most efficient use of the power and bandwidth at their disposal. Researchers have considered the relay's ability to re-generate or decode the signals that are transferred from the terminals in order to evaluate the efficacy of the different transmission technologies [2]. This has allowed the researchers to make a comparison of the various transmission methods.

The decoding operation, which is carried out in accordance with the decode and forward (DF) protocol, is the responsibility of the regenerative relay as a component. Instead of decoding the signals at the relay, the non-regenerative relay will often use an amplify-and-forward (AF) protocol. This is in contrast to the regenerative relay, which decodes the signals. In line with the specifications of this protocol, the relay is responsible for the amplification of signals before they are sent to the terminals. In cooperative systems, the usage of TS-based relaying (TSR) and PS-based relaying (PSR), both of which allow for the simultaneous transfer of energy and information, may be used as relaying methods. During the course of this investigation, a two-transceiver, one-relay AF two-way relaying system is broken down and analysed. When compared to one-way relaying, the spectral efficiency offered by two-way relaying is much greater. The two-way relay uses the energy that it has harvested from the broadcasted signals in order to both amplify and send out the “radio frequency” (RF) signals that it receives from the transceiver nodes. We make the TSR and PSR protocols available to users in order to facilitate information processing and energy collection by the relay using the preset topologies for the TS and PS receivers. This should make it simpler for the relay to carry out these tasks. We investigate the problem of optimal resource allocation and relay selection in order to maximise the potential communication rate that may be achieved between the transceiver nodes while employing either the TSR or PSR protocols. This is done in order to achieve our goal of increasing the potential communication rate. the number of available relays. This improvement may be achieved by increasing the potential communication rate. In addition to this, we build formulae for the possible SINR (signal to noise ratio) that will be present at the destination. We give the most effective strategies for power distribution, energy collecting, and relay selection for every one of these processes. In each of these scenarios, we run across an obstacle in the form of a mixed-integer programming optimization difficulty [3].

This process[6-8] may be sped up by using an estimate of the SINR that is high and estimating the instantaneous sum-rate. This allows for the production of closed form solutions. The basis for the distribution of energy is laid out by the answers to the “Karush-Kuhn-Tucker” (KKT) requirements. In, the potential throughput that can be reached at the destination is computed in order to do a performance comparison between PSR and TSR. In contrast, the focus of our research is on determining which of the PSR and TSR techniques is more successful in terms of achieving the objective of increasing the sum rate. When we look at the PSR protocol vs the TSR protocol, we find that the performance of the PSR protocol is superior in the situation of sum rate maximization. The graphs that are shown in Section IV give evidence that substantiates this assertion [4].

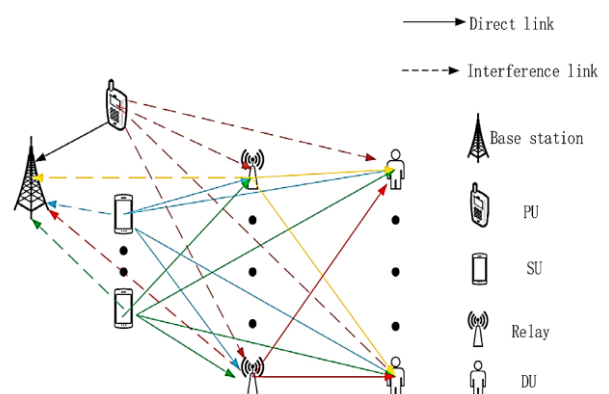


Fig 1: System Model.

We take into consideration a cooperative multi-user uplink OFDMA relay system, as shown in Figure 1, in which the primary user and secondary user coexist simultaneously. M source nodes ($S_m, m = 1, 2, M$) send the signal to their corresponding destination nodes ($D_j, j = 1, 2, J$) with the assistance of N intermediate relay nodes ($R_i, i = 1, 2, N$) and a number of subcarriers ($C_l, l = 1, 2, K$). In this manner, the signal is successfully transmitted. In all, there are N intermediate relay nodes and K subcarriers involved. In order to do this, there are a total of N intermediate relay nodes that are used ($R_i, i = 1, 2, N$). Because of the base station, all of the key users are now transmitting data in real time. It is to be anticipated that each node will only make use of a single antenna and will not simultaneously send out and receive signals. On each particular subcarrier, it is presumed that the channel is experiencing Rayleigh fading. In addition to this, the relay node operates in half-duplex mode via the use of the DF method. If the received SINR at the relay node is higher above a given threshold, then the relay may be able to analyse the incoming data in an acceptable manner. [5].

2. Review of Literature

Within the scope of this investigation, we do an analysis of a cooperative wireless network that is comprised of two

transceiver nodes that connect with one another by means of power-restricted, two-way amplify-and-forward (AF) relay nodes. Before being sent on to the transceiver nodes, the signal is first amplified by the relay nodes, which makes use of the energy that was previously present in the signal that was received. Therefore, the transceiver nodes are capable of concurrently transmitting information and energy. In order to accomplish simultaneous information extraction and energy harvesting at the relay, we study a "time switching-based relaying" (TSR) protocol in addition to a power splitting-based relaying (PSR) protocol. Relaying may be broken down into a few distinct subcategories, the most common of which are "time switching relaying" (TSR) and "power splitting relaying" (PSR). We try to find a solution to the problem of maximizing the sum-rate by imposing limits not only on the overall transmit power but also on the quantity of energy that is collected in both scenarios. In order to solve this problem, we have devised the optimal method for the distribution of resources and the selection of relays. It is determined whether or not the proposed PSR and TSR procedures are successful via the use of numerical simulations [5].

As more mobile devices connect to wireless networks, the task of lowering interference[9-10] and boosting energy efficiency in a constantly changing environment for wireless communication has grown much more difficult. The purpose of this study is to evaluate the possibilities for a multi-carrier "decode-and-forward" (DF) cognitive radio relay network to reduce its overall energy consumption. The minimum transmit rate requirement for the primary user, the relay transmit power, the signal-to-noise ratio threshold, subcarrier pairing, and relay selection are some of the constraints that apply to this network. The choice of the relay is yet another one of the constraints. Calculating EE is as simple as taking the amount of energy created and dividing it by the total amount of energy utilized. In order to accomplish this objective, a dependable strategy for the distribution of resources has been presented. When channel uncertainty is factored in, the mixed binary integer programming issue, which was the primary optimization challenge, is shown to be a non-convex problem. This conclusion was reached after the problem was first posed. After that, using the Dinkel-Bach approach, we take the non-convex issue that we started with and transform it into a problem that is quasi-concave. This is done in order to assist it in better handling the unpredictable nature of the channel. We are able to solve the NP-hard problem in two parts by first modifying the subcarriers to get the best relay selection and then allocating the subcarriers in line with the results of that selection. This allows us to tackle the problem in a manner that is more manageable. Because of this, we are now in a position to tackle the problem in a manner that is more manageable. As a direct consequence of this, we are

now in a position to tackle the problem in a manner that is more tractable. Because of this, we are now in a position to tackle the problem in a manner that is more manageable. This allows us to tackle the problem in a manner that is more manageable. Because of this, we are now in a position to tackle the problem in a manner that is more manageable. Because of this, we are now in a position to tackle the problem in a manner that is more manageable. By using the dual decomposition strategy, it is possible that we will be able to give a solution to the problem that is almost flawless. The findings of the simulation indicate that the joint resource allocation plan that was recommended fulfils the required requirements for service quality, and that the degree of energy efficiency that may be achieved is greater than that of some projects that are currently being worked on. In addition, the scalability of the resource allocation scheme is shown by the increased convergence performance of the resource allocation algorithm that was recommended for use with a variety of topologies [6].

Within the scope of this research project, we investigate a cooperative method that is both energy-efficient and effective for "energy harvesting wireless sensor networks" (EH-WSN). By integrating the functions of power distribution and relay selection, this method achieves the highest possible level of energy efficiency. The development of a simple heuristic approach was the primary contribution that we made to an EH-WSN that was based on clustering. This approach was designed to increase the energy efficiency of each individual node. We create a nearly perfect solution to an online optimization problem that calls for the lowest possible level of computer complexity to solve it. This is accomplished after first determining the influence of cooperative communication and then taking into account the energy sustainability of each node in the network. The results of an in-depth simulation are presented to illustrate how well our proposed method works in terms of the distribution of transmitting power among the nodes and the overall utility that the network provides. As a consequence of this, there is reason to be positive about the future of practical applications including the joint optimisation technique.[7].

As a consequence of ongoing advancements in wireless technology, the Wireless Sensor Network, often known as WSN, is in a state of perpetual flux. The level of energy consumption and the amount of data that may be sent across the network are the two primary regulating goals of the WSN. As a result of this study, a new approach for selecting relay nodes that is based on fuzzy inference algorithms (RNSFIA) was proposed with the intention of finding a middle ground between these two purposes. RNSFIA places a higher priority on this distance, in addition to the amount of communication that occurs

concerning intermediate nodes and the communication distance that exists between nodes. It also gives priority to the residual energy that is associated with the nodes. In order to do this, it was necessary to choose a new relay node for each cycle of transmission while simultaneously enhancing a variety of levels and objectives. In addition, a technique known as MLEACH (Modified Low Energy Adaptive Clustering Hierarchy) is applied in order to examine the results side-by-side and draw comparisons between them. The performance of the RNSFIA that has been suggested not only increases the network's lifetime by 50–60%, but it also increases the throughput of the network by 35–40%. We recommend adding additional communication bandwidth-related levels and goals in order to maximise the effective use of the available network resources and further optimise the most efficient use of those resources. [8].

Within the framework of cooperative wireless "simultaneous wireless information and power transfer" (SWIPT) networks, this research investigates resource allocation algorithms that are effective in terms of the quantity of energy that they draw from their own networks. In addition to the power that is being sent, the SWIPT relays are exploited in order to boost the energy efficiency of the destination node. In a power-splitting SWIPT design, the "decode-and-forward" (DF) and "amplify-and-forward" (AF) relay designs are both used in order to get the best possible results in terms of relay selection and power distribution. These structures are referred to by their acronyms, which are "Decode-and-forward" (DF) and "Amplify-and-forward" (AF). Both the DF and AF relay types provide non-convex challenges when it comes to the question of how to improve their energy efficiency. Using closed-form equations, one is able to figure out which power splitting ratios are optimal for DF and AF relays. These ratios are, in turn, determined by the signal-to-noise ratios present at the destination node [9]. The optimal power splitting ratio is used in the construction of relay selection procedures. These strategies may be completely or partly aware of the channel state information depending on their design. In addition, by making use of the one-of-a-kind nature of the streamlined optimization problem in conjunction with the power and quality of service restrictions, an innovative method for the allocation of power is developed, and its application is shown. The results of the simulation suggest that the suggested method for selecting relays is more energy-efficient than the traditional methods. Based on these findings, it is clear that the resource allocation technique that was proposed achieves the highest possible level of energy efficiency while simultaneously requiring the lowest possible level of computer complexity. [10].

3. System communication model

We study a wireless cooperative network that has two transceiver nodes designated as T1 and T2 that both broadcast information in both directions. The connectivity between the transceivers is achieved by the use of a single relay node. It was selected from a pool of L different relay nodes. Every single node incorporates a single antenna into its design. For the purpose of reclaiming usable energy from the RF broadcast, we provide two unique ways for relaying information: the PSR and TSR procedures respectively. Both of these protocols are built on receiver designs that employ either time switching or power splitting, depending on which protocol you're looking at. In the parts that are to follow, we are going to provide an in-depth review of both the PSR process and the TSR process.

❖ Protocol for Power Splitting-Based Relaying (PSR)

When it comes to PSR, there are two time slots that are used for communication between the various transceiver nodes. Both of the transceiver nodes will use their best efforts to transmit a signal within the allotted initial time slot. After then, the relay will pick up the signals that were transmitted. Let's say that the transmit signals that are being delivered by the two transceiver nodes T1 and T2 are, respectively, x_1 and x_2 . Since $||$ denotes absolute value and E is the expectation operator, it is presumed that $E|x_1|^2 = E|x_2|^2 = 1$ since these two symbols go together. The signal, which is denoted by r_i and was picked up by the i th relay, may be described in the following manner:

$$r_i = \sqrt{P_1}h_i x_1 + \sqrt{P_2}g_i x_2 + \delta_i, \quad 1 \leq i \leq L$$

If the variables P_1 and P_2 stand in for the transmit powers of T1 and T2, respectively, and if the variable i represents the "additive white Gaussian noise" (AWGN) at the i th relay, then the channel gains that are provided by T1 and T2 are represented by h_i and g_i , and P_1 and P_2 represent the transmit powers of T1 and T2, respectively. The signal that was received by the i th relay is cut in half during the second slot. This is done so that, depending on which half is selected, the signal may be utilised for either the processing of information or the harvesting of energy, depending on whatever function is required at the time. Let's say that the power splitting ratio is $[0, 1]$, which means that r_i is employed for energy harvesting, and $p(1)$ r_i is utilised for information processing. The expression for the overall quantity of energy collected at the i th relay, denoted by $PEH(i)$, is as follows:

$$\begin{aligned} P_{EH}(\rho) &= \rho\eta\mathbb{E}\{|r_i|^2\} \\ &= \rho\eta[P_1|h_i|^2 + P_2|g_i|^2 + \sigma_{\delta_i}^2] \end{aligned}$$

❖ The Time Switching-Based Relaying (TSR) Protocol

As can be seen in Figure 2, the transmission block time T is generally divided into two halves with the same amount of time, and these two halves are denoted by the symbols T and $(1) T$ respectively. The relay node will continue to gather energy from the signals it receives for a period of time denoted by the variable T , in which the values 0 and 1 will, respectively, stand for. The time that is still available from the most recent block, $(1) T$, is then divided into two halves that are of equal duration. During the first half of the total transmission period, which is represented by the notation $(1) T/2$, data is sent from the source to the relay. After the processing is complete, the second half of the time, also represented by the notation $(1) T/2$, is spent with the data being transported from the relay to the destination. After the block has been cut into equal halves and each of those halves has been eaten, the amount of time that is left over will be cut in half.

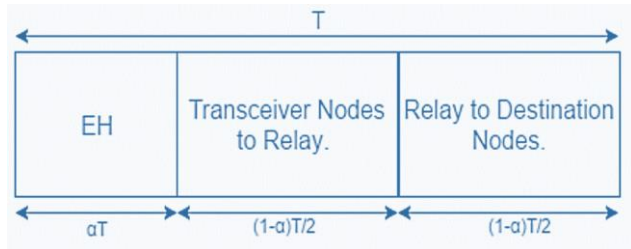


Fig 2: Protocol Transmission Time-Block Structure Of The Tsr Protocol

Let's say that the transmit signals that are being delivered by the two transceiver nodes T1 and T2 are, respectively, x_1 and x_2 . It is presumed that the equation $E | x_1 |^2 = E | x_2 |^2 = 1$ is correct. It is possible to write the signal that was acquired by the i th relay as " r_i ," which stands for "relay it."

$$r_i = \sqrt{P_1} h_i x_1 + \sqrt{P_2} g_i x_2 + \delta_i, \quad 1 \leq i \leq L$$

During a period of time shown by the notation T , energy is extracted from the signal that was received, and at the relay node, the energy that was extracted is represented as.

4. Research Methodology

Evaluation of the performance of optimisation techniques based on MATLAB. The experiment may continue after the "EHGUC-OAPR" routing protocol has been loaded and either the clusters have formed or an EHWSN with 200 nodes has been deployed in a monitoring area that is 500 metres by 500 metres. In this section, Table 1 lists certain particular parameters.

TABLE 1: SIMULATION PARAMETERS

Parameter	Value	Parameter	Value
Target BER Pb end-to-end	3-Oct	Bit rate Rb	10 kb/s
Source-relay target BER P _{sr}	4-Oct	Transmission power PCCT tx	98.2 mW
Exponent of the path loss	3.5	density of the power spectrum of the noise N ₀	-171 dBm/Hz
The average peak to valley ratio E	1	PCCT reception power at the rx frequency	109.5 mW
The effectiveness of the RF n drain	0.35	PEH,n The rate at which energy is harvested	1 mW
O, H	0.1, 5	Lref is an abbreviation for "reference route loss."	10° (90 dB)

Simulations are done in order to verify the approach that achieves the most dependable maximum energy efficiency. In this paper, we investigate cooperative multiple subcarriers, multiple relays, and a total of five secondary users distributed among two relay nodes, eight subcarriers, and eight destination nodes in OFDMA communication networks with multiple secondary users. The primary users' base stations are located in the coordinates (0, 26), (26, 10), (30, 5), and (20, 5), respectively. These are the coordinates for the secondary users. The coordinates (0, 26) denote the location of the principal user's home base station in the network. Those numbers provide information on the locations of the relay nodes that are associated with the addresses (40, 10) and (50, 5). (80,30), (87,20), (83,10), (90,5), (85,15), (75,5), (85,0), and (92,5) are the relative coordinates of the destination nodes. The particular system parameters are detailed in Table 2.

Table 2: System Parameters.

Variable	Value
α	5
β	5
γ	4.95
ϵ_1	0.6
ϵ_2	0.03
N_0	11 -11
$K_{sm,ri}$	0.7

$K_{sm,dj}$	0.7
$K_{ri,dj}$	Random variable in [0, 2]
$K_{sm,b}$	0.5
$K_{ri,b}$	0.5
$K_{p,b}$	0.5
$K_{p,dj}$	0.5
$\lambda(1)$	6
$\mu(1)$	0.2
P_{max}	4 W
P_{sm}	0.3

You will have the ability to specify the path-loss coefficient that exists between the main user P and the destination node Dj if you choose this option and then follow the instructions that appear on the screen. It is put to use to indicate the path-loss coefficient that exists between the destination node Dj and the relay Ri. Additional factors are not discussed in this article. This parameter provides an indication of the path-loss

coefficient that exists between the secondary user Sm and the destination node Dj.

5. Analysis and Interpretation

In this part of the article, we are going to have a look at the throughput figures that SWIPT was capable of achieving in the multi-hop network. The distance from the source to the destination is DSD metres, which may also be expressed as d_{D1} in SD metres. There are i identical relays, which can either be AF or DF. We make the assumption that all of the relays, i and i , have identical EH ratios, and we specify the parameters as DSD 5 m, 1, T 1, 2, 0.01 2 2 ia ic. The results shown here are the average of between 6 and 10 different channel realizations. When compared to AF relaying, DF relaying gives a larger throughput; however, this comes at the price of an increase in the amount of noise amplification, an accumulation of errors, and an increase in the amount of power required at the relays for the transmission of signals. This lends credence to the argument that the conclusion is correct since, in light of the circumstances at hand, it makes perfect sense. The EH ratio of the DF network is higher than that of the AF network due to the fact that the information in the DF network has to be decoded and recoded on a more frequent basis. Table 3 presents a breakdown of the throughput of multi-hop networks for a variety of relay count configurations.

Table 3: Compliance Perfecte With Eh Protocols And The Application Of Such Protocols

Number of relays (i)	T_{opt}			
	AF _{TSR}	AF _{PSR}	DF _{TSR}	DF _{PSR}
1	1.2475	0.6556	1.3395	0.8636
2	1.5983	1.0933	3.8763	1.6497
3	2.493	2.1525	2.0532	3.1496
4	3.5393	4.2196	4.6987	4.9981
5	5.7078	5.8356	5.6554	6.1448

When the signal-to-noise ratio (SNR) is low, the performance of TSR is superior than that of PSR. On the other hand, when the SNR is high, the performance of PSR is superior to that of TSR. This pattern remains consistent even as the number of relays increases. When

contrasted with the SWIPT-AF network, the SWIPT-DF network possesses a higher throughput. The throughput that we were able to achieve on a network consisting of three hops is shown in Table 4. Because of improvements made to the EH ratios, this is now possible.

Table 4: A 3-Hop Network's Throughput With Optimal Eh Ratios

Currently used relays (i)	Currently used relays (i)	TSR			PSR		
		a_1	a_2	T_{opt}	β_1	β_2	T_{opt}
	AF	0.3169	0.2225	2.4181	0.6196	0.5265	1.5217
2	DF	0.3531	0.2689	3.0365	0.6392	0.5254	2.109

By using ideal EH ratios, relays are able to choose an appropriate amount of time or power (TSR/PSR) for EH. This allows for greater efficiency. As a consequence of this, the relays are in a position to store the vast majority of the energy for relays that will function at a later time. It has been shown that in terms of throughput, a network that has an ideal EH ratio performs better than a network that possesses a uniform EH ratio.

6. Result and Discussion

The efficiency of the transmitting power allocation block is the first aspect that we are going to investigate. It is assumed that the source cluster head S, the relay node R, and the destination node D are all located in a line while operating in an environment with just one dimension. This idea is supported by the observation that D is located some distance away from S, given that S serves as the origin and

is situated some thirty metres from where D is located. This assumption is based on the fact that the one-dimensional state has only one dimension. This is done on the basis that S acts as the origin. This assumption is based on the fact that the state only has one dimension. The relay R is also considered to be in this situation. We are able to achieve the numerical shifts in the ideal power distribution by progressively adjusting the value of R. In the end, we make an effort to solve equation 26, and after that's done, we compare the results with the unsatisfactory solutions that were recommended to us, before going on to the one-dimensional circumstances. The disparity in total transmission energy (ES plus ER plus TX plus OPT) between the two is compared and shown in Table 5.

Table 5: An Analysis Of The Differences Between The Best Possible Results And The Best Possible Secondary Results

PSR	-3	-1.6	-2	-0.9	1	0.9	0	1.6	3	3.6	5	3.6
TSR	11.2	9.8	6.9	5.6	3.5	2.6	2.9	4.5	6.5	8.6	11	13.6

When relay R is positioned such that, it is exactly in the middle of relays S and D, we are able to see that the difference falls to its lowest point, and the relative error that is connected with it is reduced by around 5%. Therefore, the computerised method of optimisation that was presented is both useful and accurate enough.

The benefits of the numerically simulated strategy proposed here for selecting relays and distributing power optimally while also collecting energy are emphasised. This technique combines energy harvesting with optimal power distribution. This demonstrates that our plan is working really well. Parallel performance analyses of the PSR and TSR procedures are carried out in this study. We are going to assume that Rayleigh fading happens over the whole board.

The initial step of this process is determining how effectively the recommended systems function in relation to the greatest possible rate and the lowest possible threshold for energy collecting. The following table provides more explanation of the total transmit power limits that apply when PT equals 30 dB and when PT equals 20 dB, respectively. Tables are used to display this information. The amount of electricity that must be present for energy harvesting to take place is between one and 10 milliwatts. Figure 3 illustrates the potential outcomes that may be attained as a result of the performance. It can be shown that the PSR system operates more effectively than the TSR method. The high rates that are shown in Figure 3 provide credence to the high SINR estimate that was employed before.

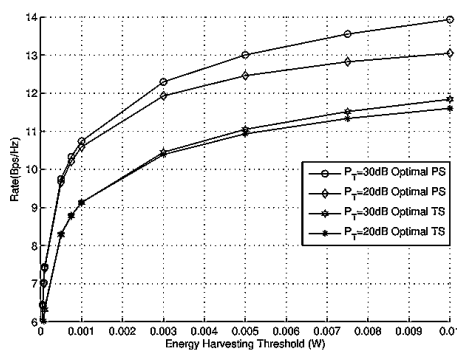


Fig 3: Rate Vs. Energy Harvesting Threshold For Various Pt Values

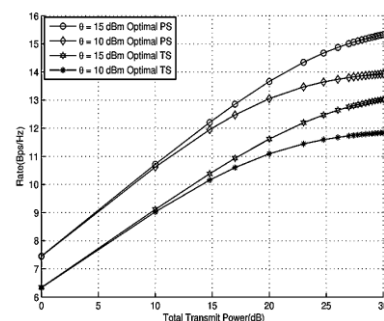


Fig. 4 Rate In Relation To The Total Transmit Power (Pt) For A Variety Of Values Of

Second, we demonstrate the effectiveness of the offered approaches by contrasting the rate with the total amount

of power that is transferred by the transceivers. The findings are displayed below for an energy harvesting threshold value of 15 dBm as well as a value of 10 dBm. There is a range of total transmitted power (PT) available ranging from 0dB to 30dB. Figure 4 illustrates the results that may be expected from the performance. As was predicted, we can observe that an increase in transmit power results in a corresponding rise in the rates. From what is shown in Figure 4, we may deduce that the PSR system operates more effectively than the TSR approach.

7. Conclusion

A wireless cooperative network that first amplifies the RF signal it receives, then gathers energy from the transmission, and then delivers the signal to the destination node through a two-way relay node is said to utilise very low total energy. The PSR protocol and the TSR protocol are two examples of potential tactics that might be used to improve the wireless energy harvesting and information processing capabilities of the relay. These capabilities could be enhanced via the employment of either of these strategies. These two methods are samples of possible strategies that may be employed in the situation. These capabilities might be enhanced via the usage of either of these protocols. We investigated the difficulty of distributing the network's resources among the relays with the highest degree of dependability. As a result of this, this method may be easily implemented into real-world applications (such as solar power monitoring systems), and it serves as the basis for an efficient and straightforward EH-WSN cooperation approach. It is possible to couple it with other optimisation protocols in order to realise the goal of achieving network-wide cooperation that is both energy-efficient and cost-effective. The results of the numerical simulations reveal that the proposed method for resource allocation improves user energy efficiency while simultaneously reducing the amount of complexity involved.

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